

# Data Mining Techniques

CS 6220 - Section 3 - Fall 2016

## Lecture 18: Time Series

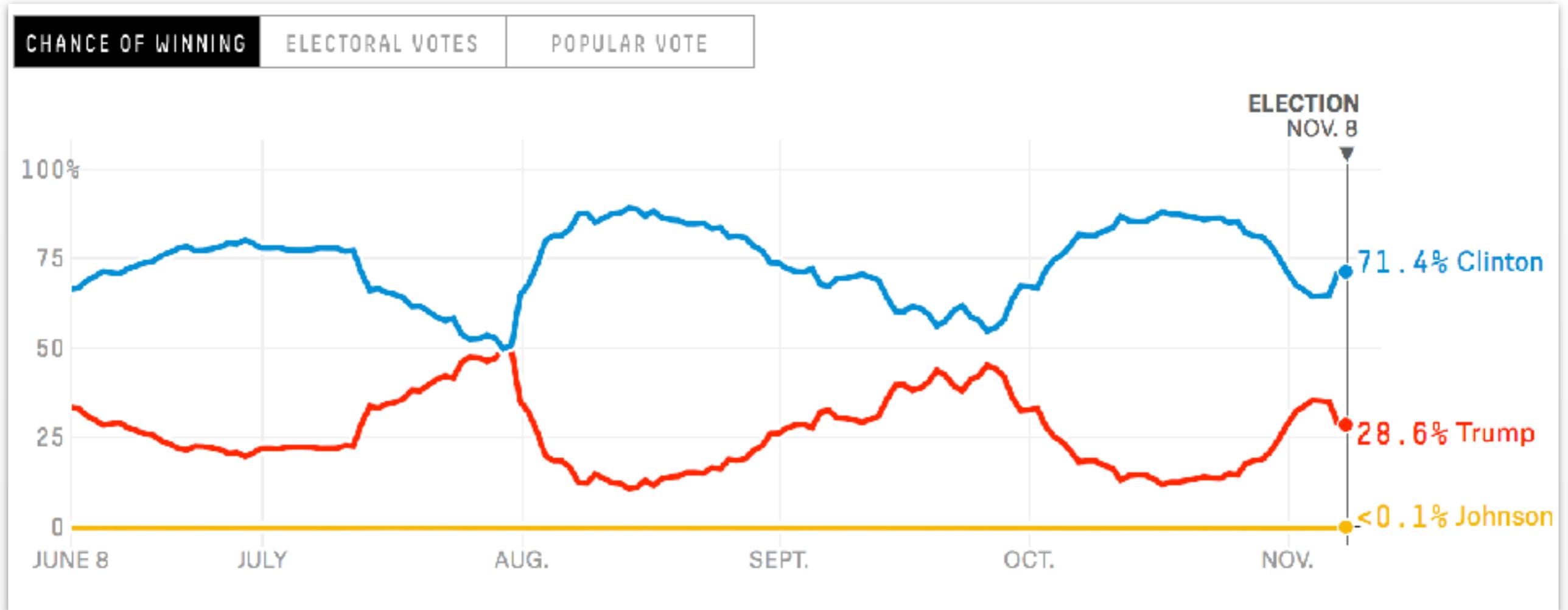
Jan-Willem van de Meent  
(*credit: Aggarwal Chapter 14.3*)



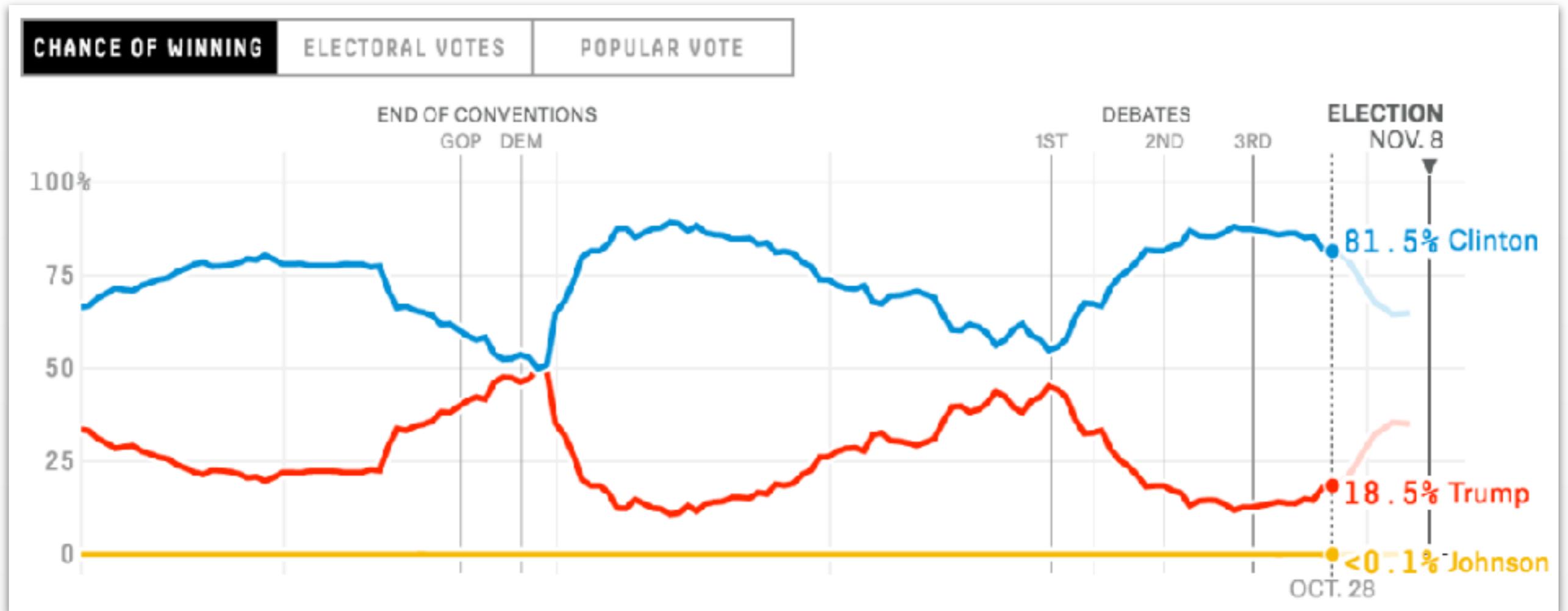
# Time Series Data



# Time Series Data

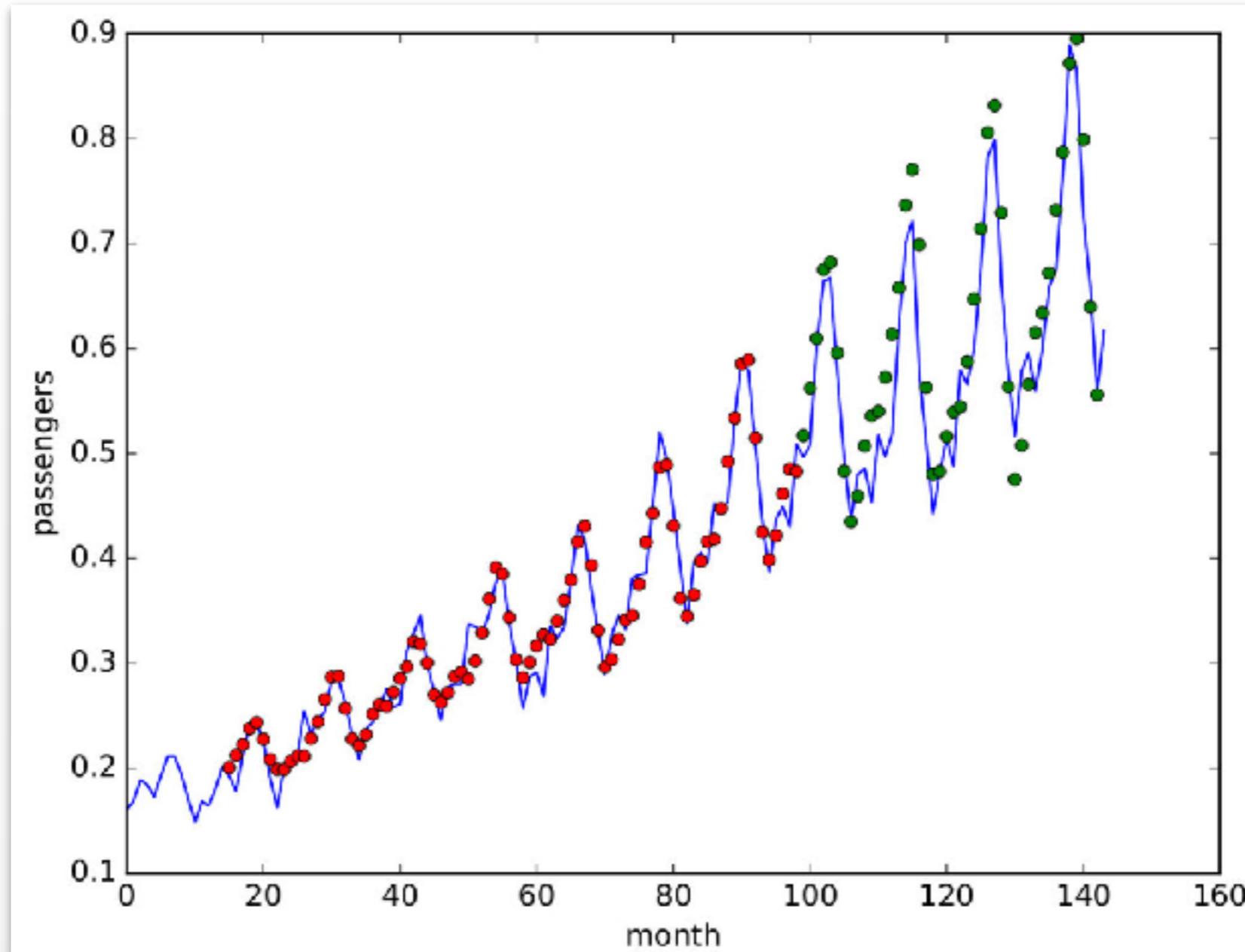


# Time Series Data



- Time series forecasting is fundamentally hard
- Rare events often play a big role in changing trends
- Impossible to know how events will affect trends (and often when such events will occur)

# Time Series Data



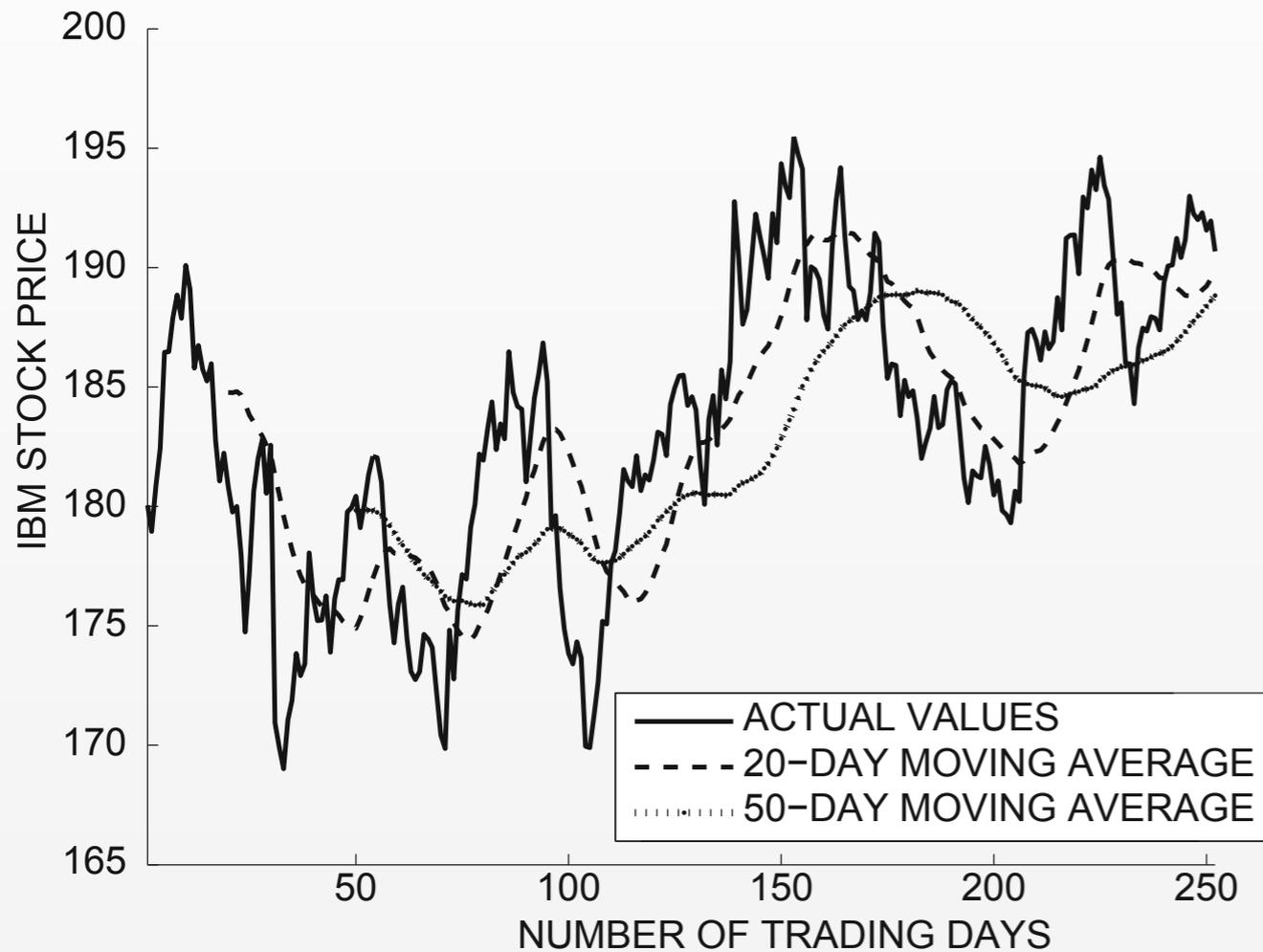
source: <https://am241.wordpress.com/tag/time-series/>

- In some cases there are clear trends (here: seasonal effects + growth)

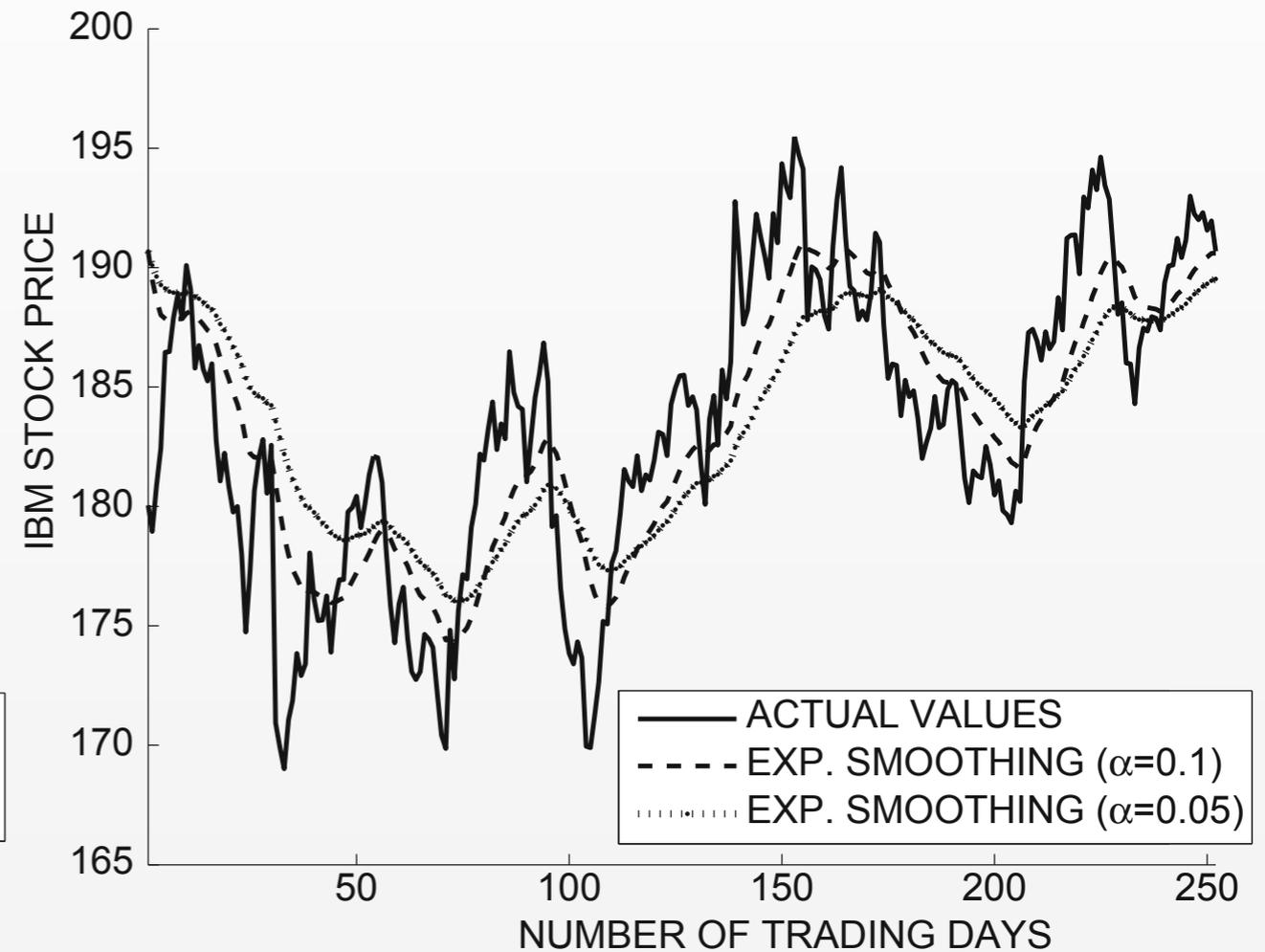
# Autoregressive Models

# Time Series Smoothing

## Moving Average



## Exponential



$$y'_i = \frac{1}{k} \sum_{n=0}^{k-1} y_{i-n}$$

$$y'_i = \alpha \cdot y_i + (1 - \alpha) \cdot y'_{i-1}$$

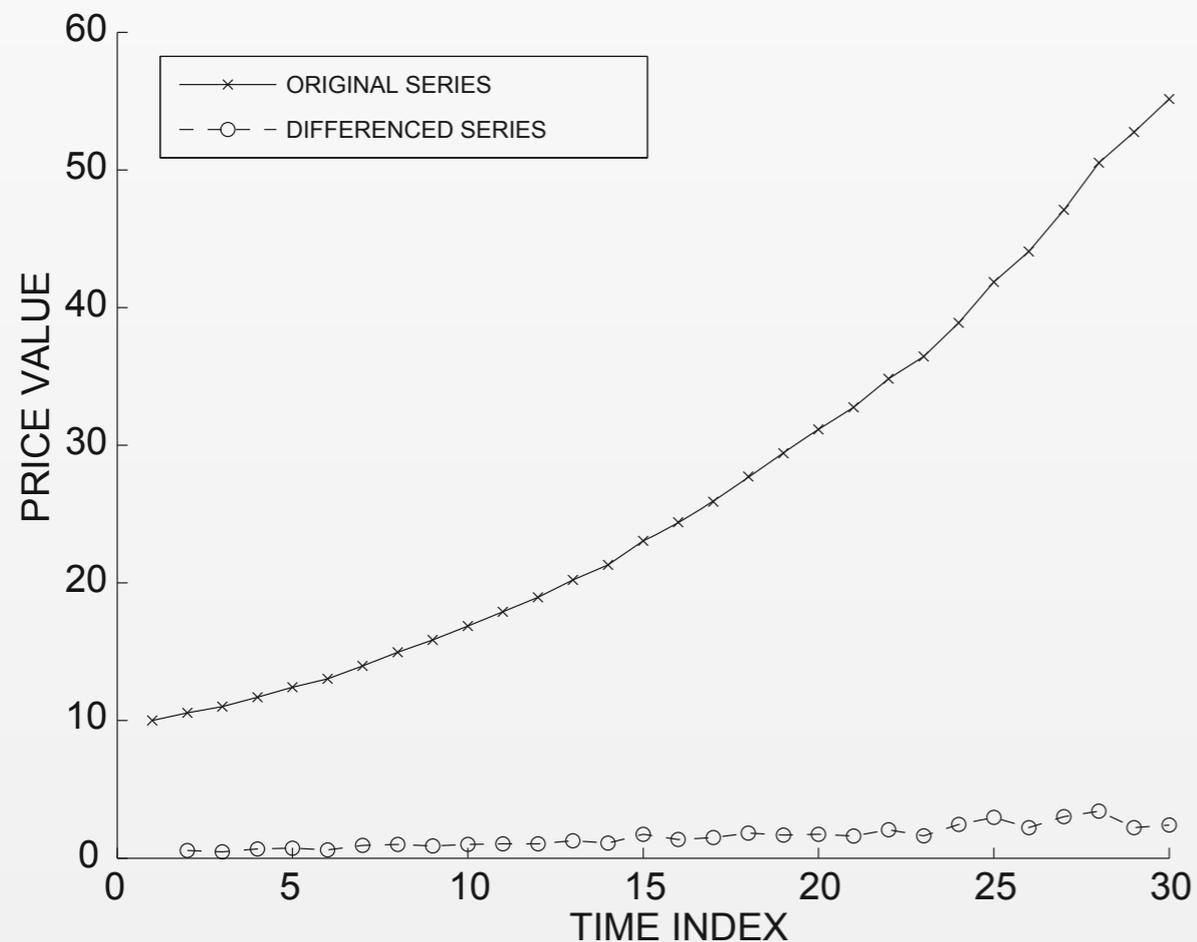
# Stationary Time Series

$$y_t = c + \epsilon_t$$

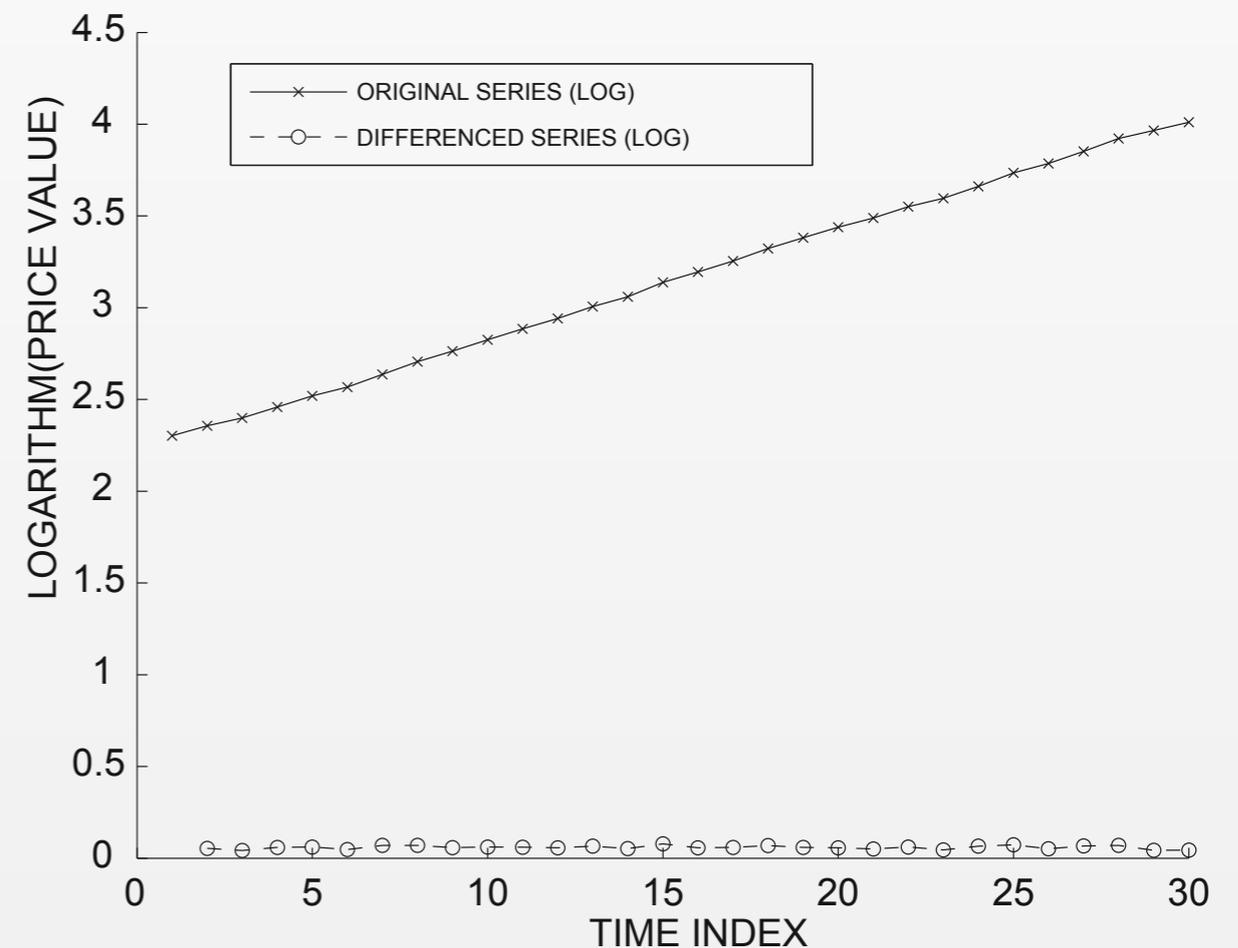
$$E[\epsilon_t] = 0$$

**Definition 14.3.1 (Strictly Stationary Time Series)** *A strictly stationary time series is one in which the probabilistic distribution of the values in any time interval  $[a, b]$  is identical to that in the shifted interval  $[a + h, b + h]$  for any value of the time shift  $h$ .*

## Differencing $y_t - y_{t-1}$

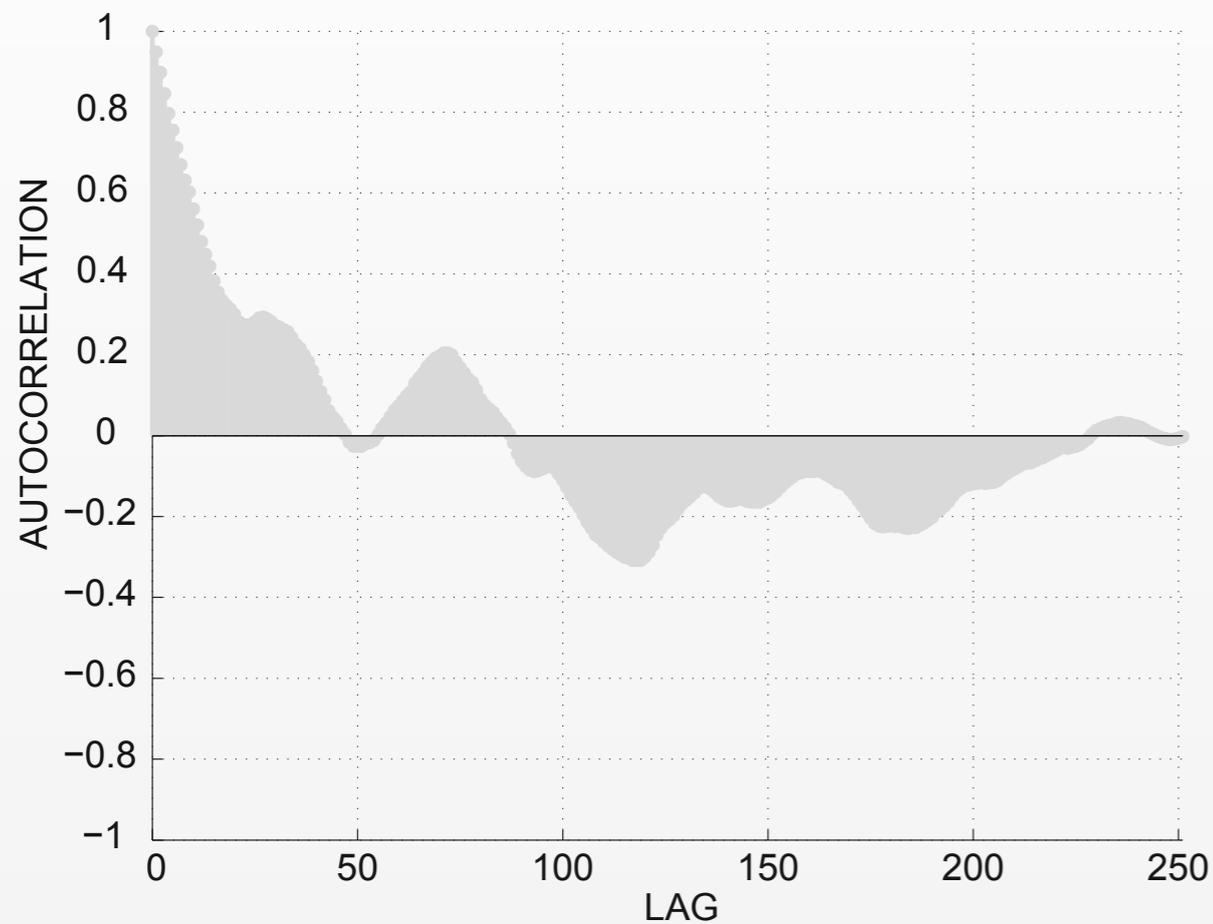


## Log differencing $\log y_t - \log y_{t-1}$

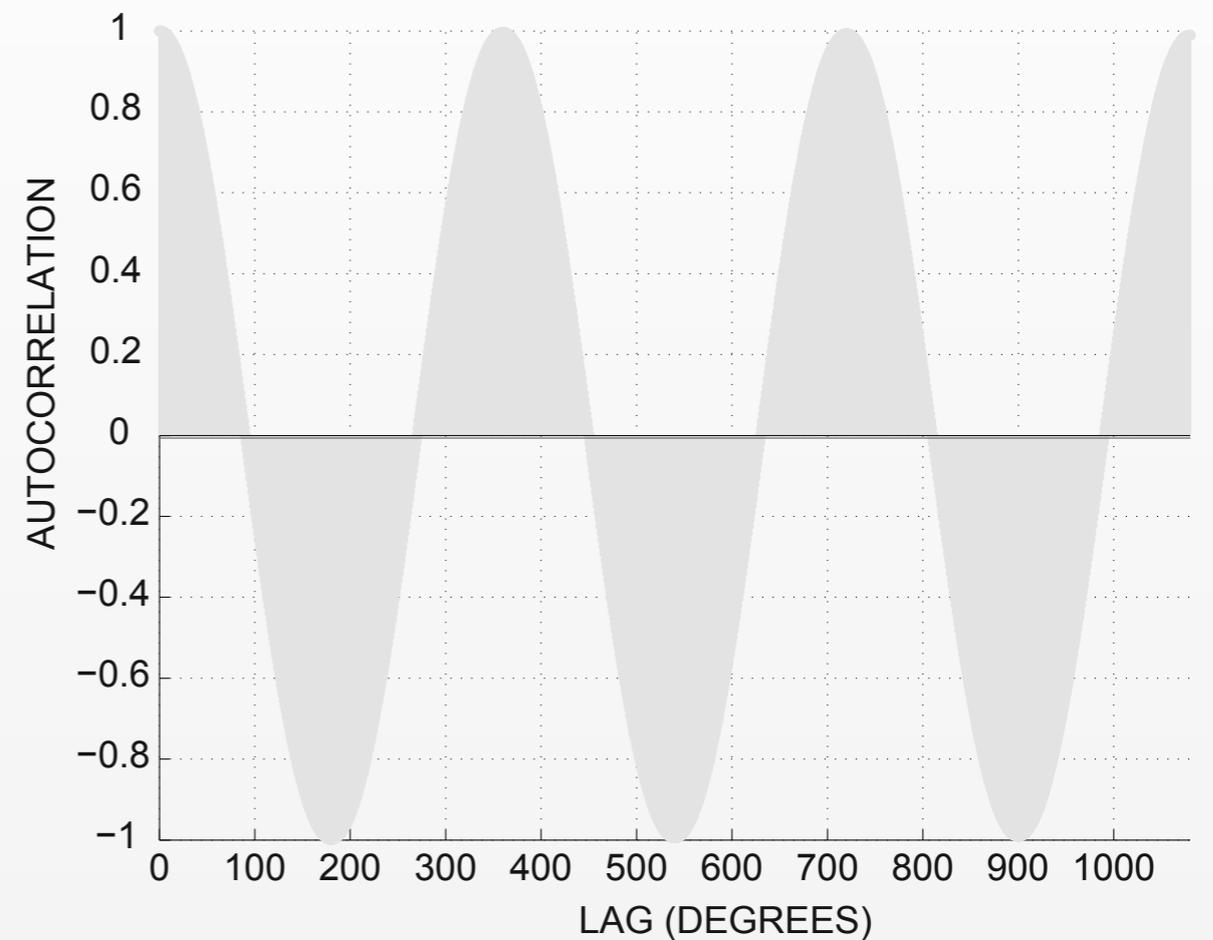


# Auto-correlation

IBM Stock Price



Sine Wave



$$\text{Autocorrelation}(L) = \frac{\text{Covariance}_t(y_t, y_{t+L})}{\text{Variance}_t(y_t)}.$$

# Autoregressive Models

Autoregressive: AR(p)

$$y_t = \sum_{i=1}^p a_i y_{t-i} + c + \epsilon_t$$

Moving-Average: MA(q)

$$y_t = \sum_{i=1}^q b_i \cdot \epsilon_{t-i} + c + \epsilon_t$$

Autoregressive moving-average: ARMA(p,q)

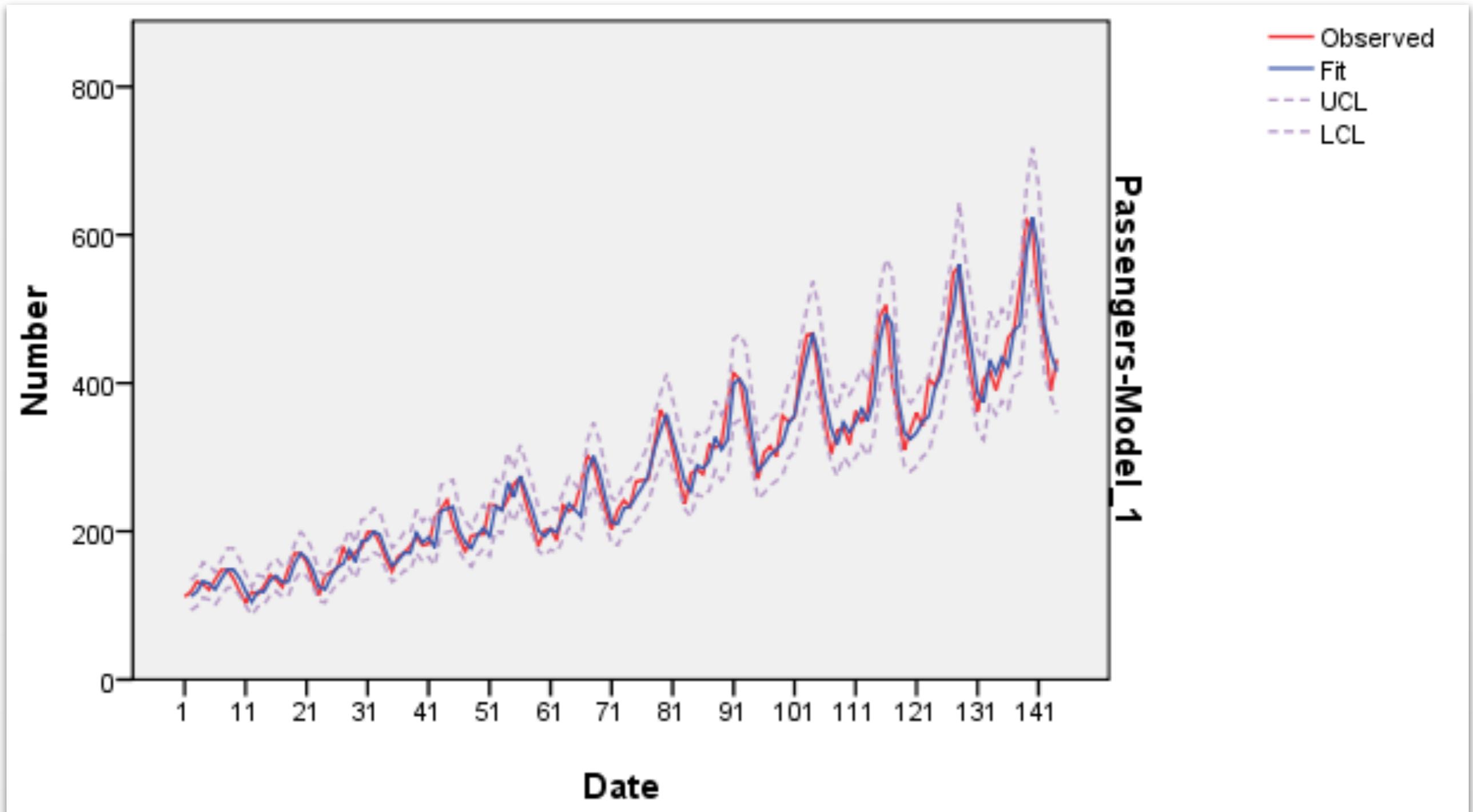
$$y_t = \sum_{i=1}^p a_i \cdot y_{t-i} + \sum_{i=1}^q b_i \cdot \epsilon_{t-i} + c + \epsilon_t$$

Autoregressive integrated moving-average: ARIMA(p,d,q)

$$y_t^{(d)} = \sum_{i=1}^p a_i y_{t-i}^{(d)} + \sum_{i=1}^q b_i \epsilon_{t-i} + c + \epsilon_t$$

Do least-squares regression to estimate a,b,c

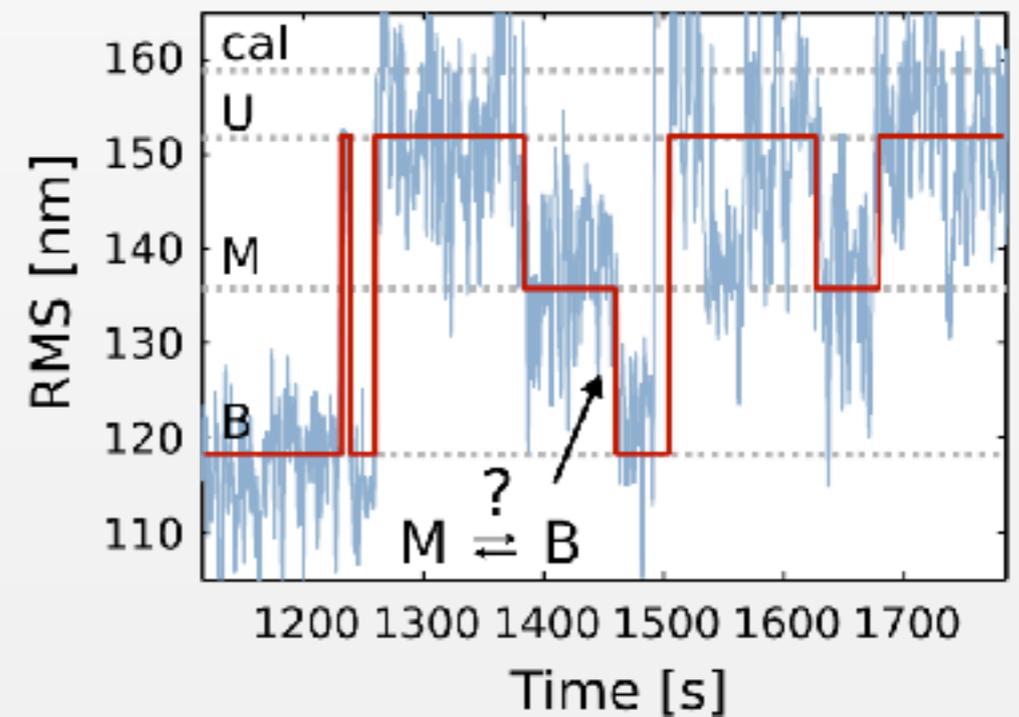
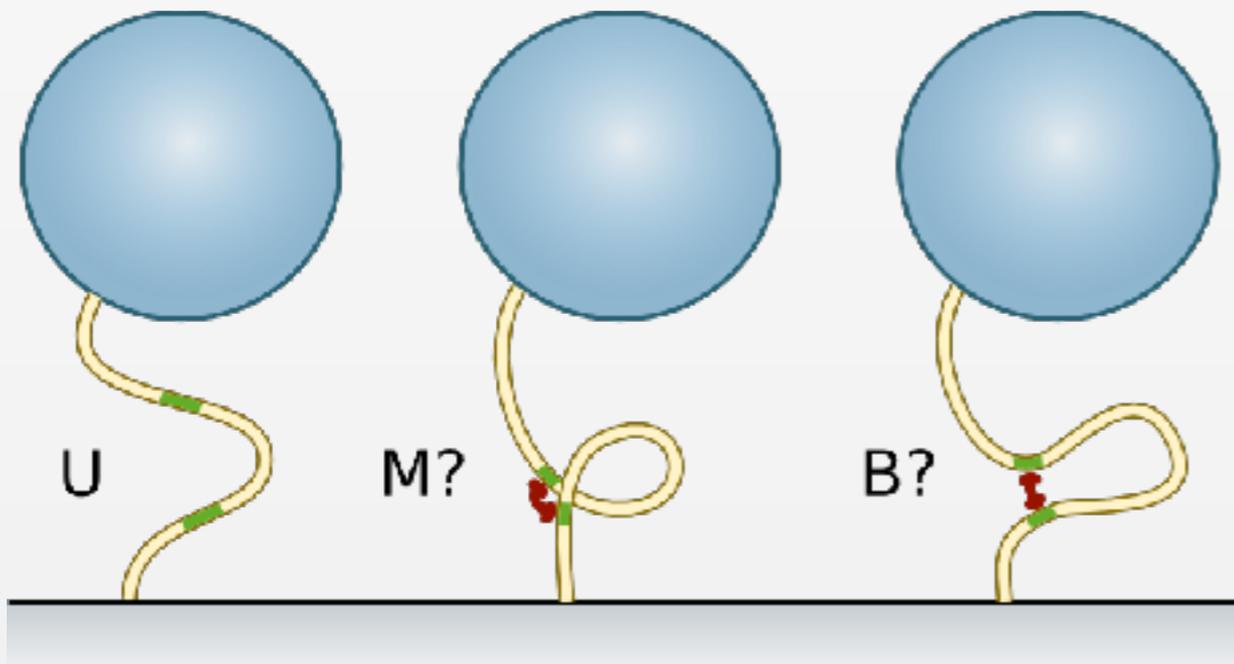
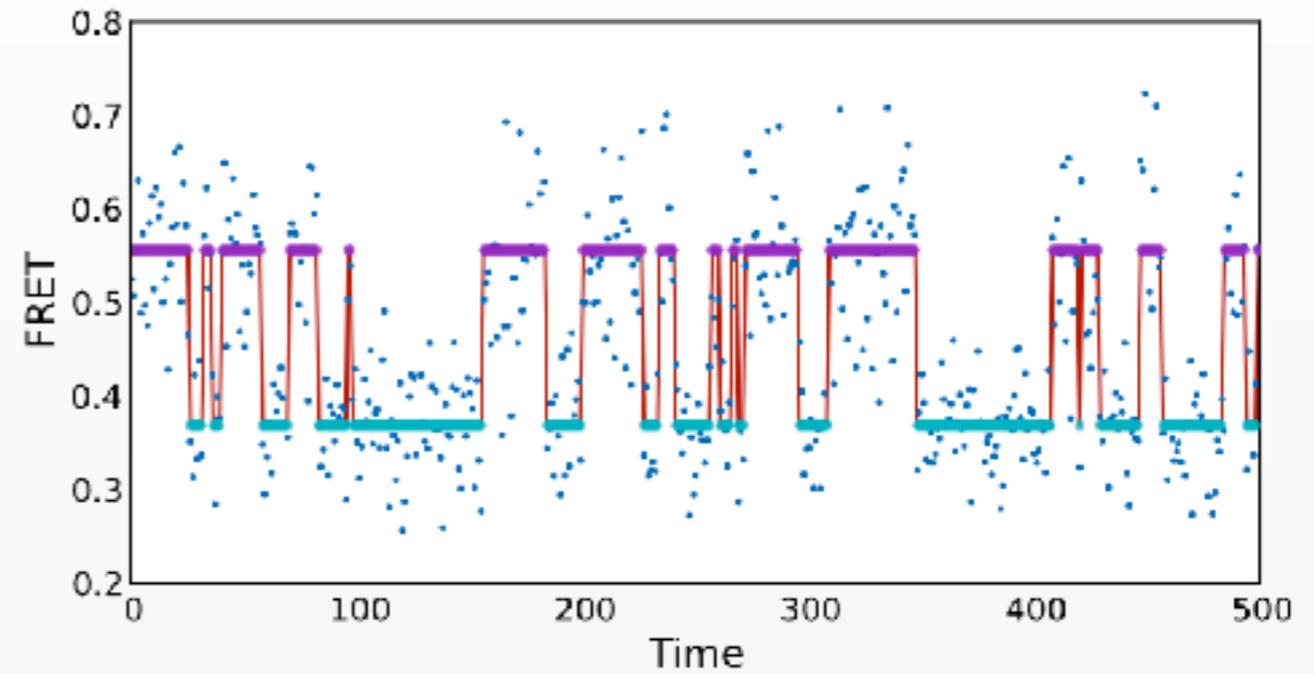
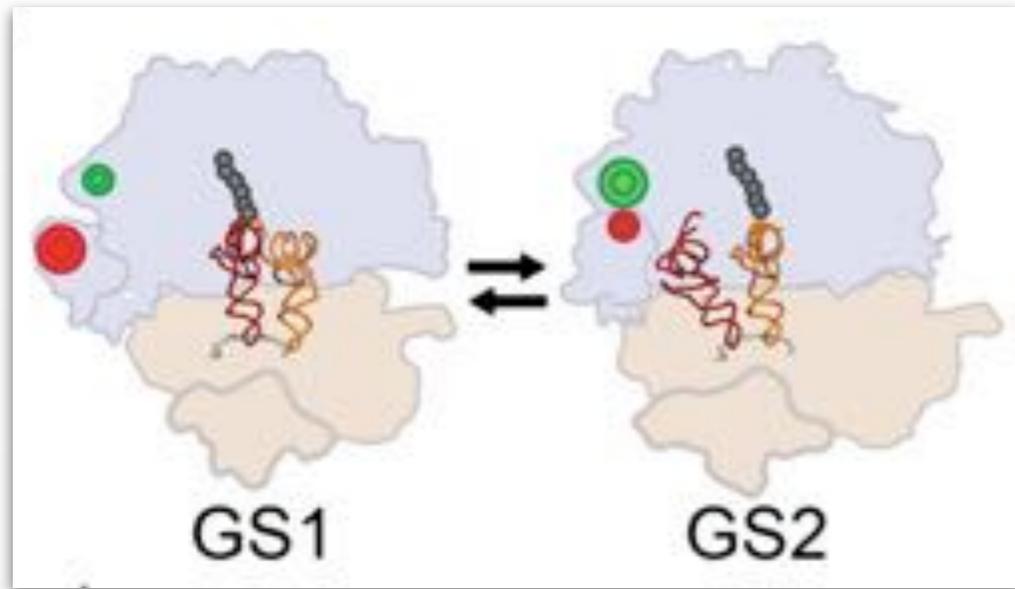
# ARIMA on Airline Data



$$(p, d, q) = (0, 1, 12)$$

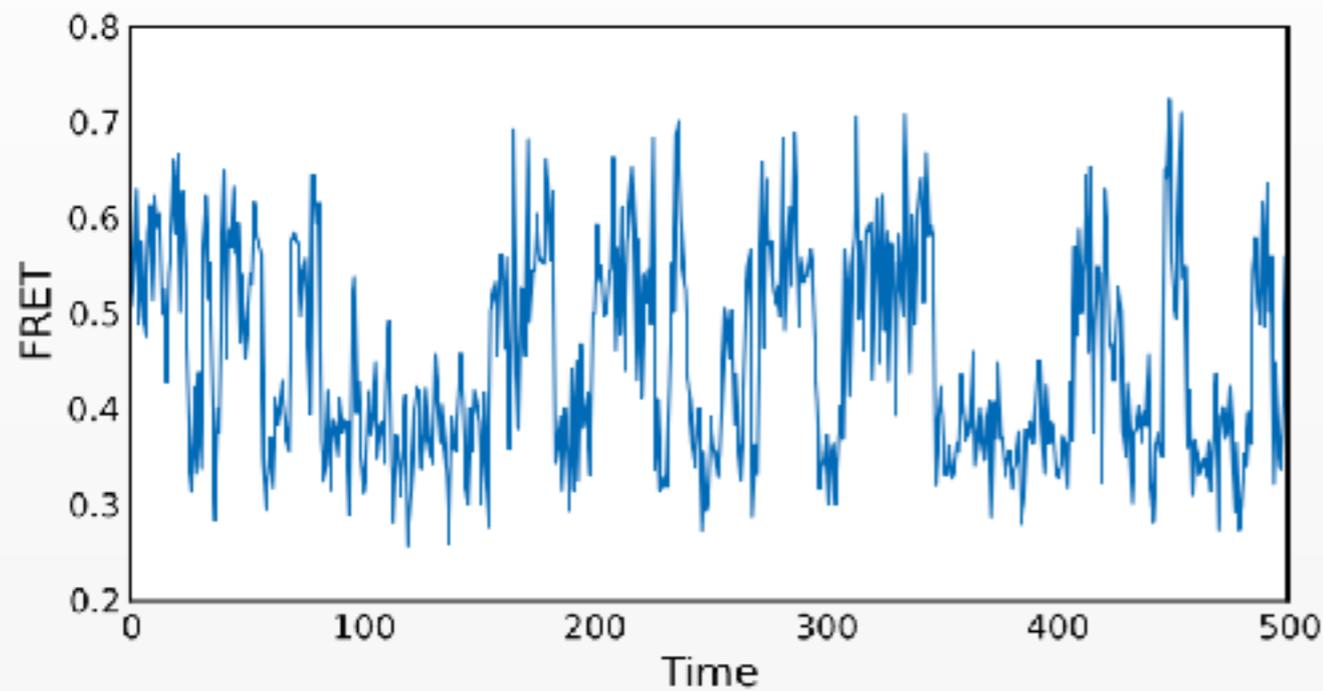
# Hidden Markov Models

# Time Series with Distinct States

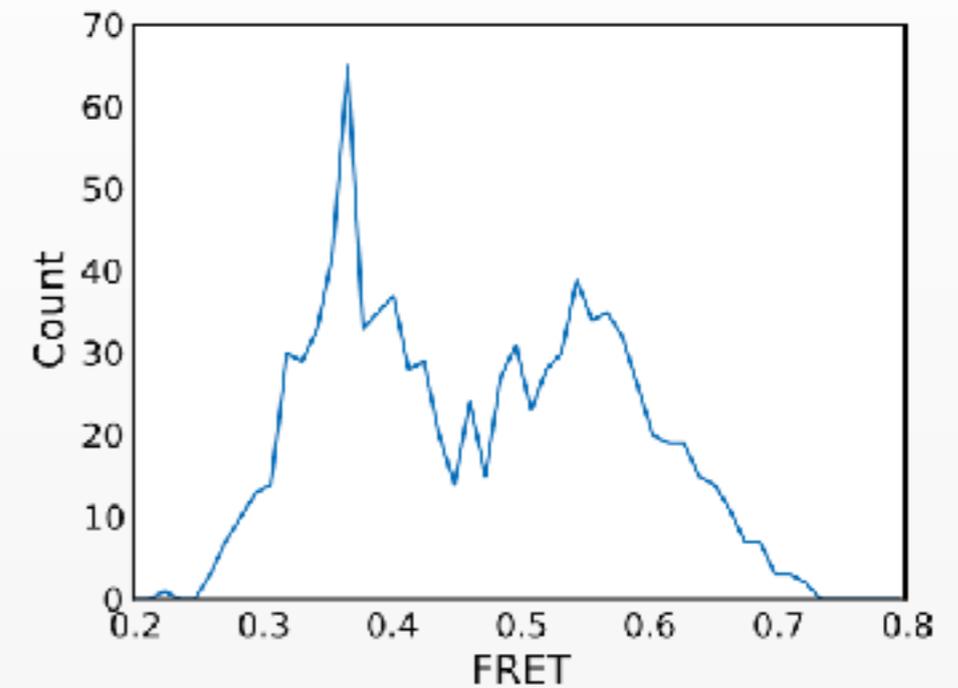


# Can we use a Gaussian Mixture Model?

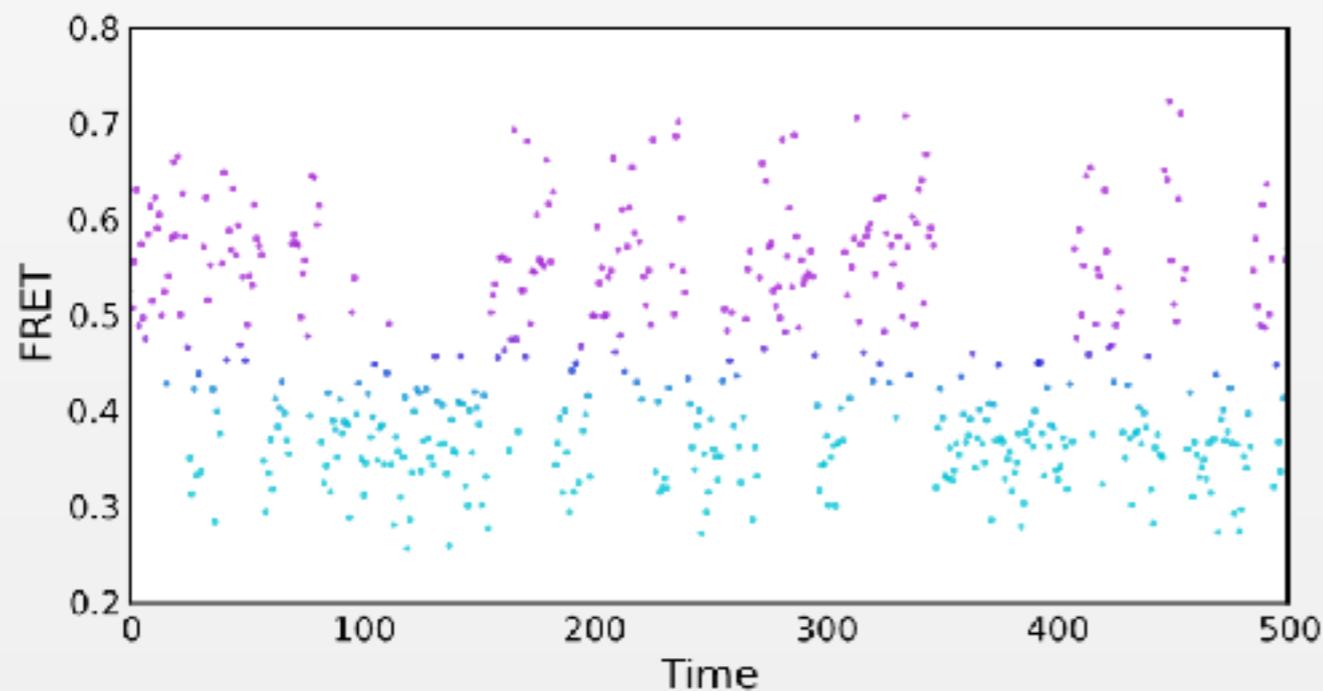
## Time Series



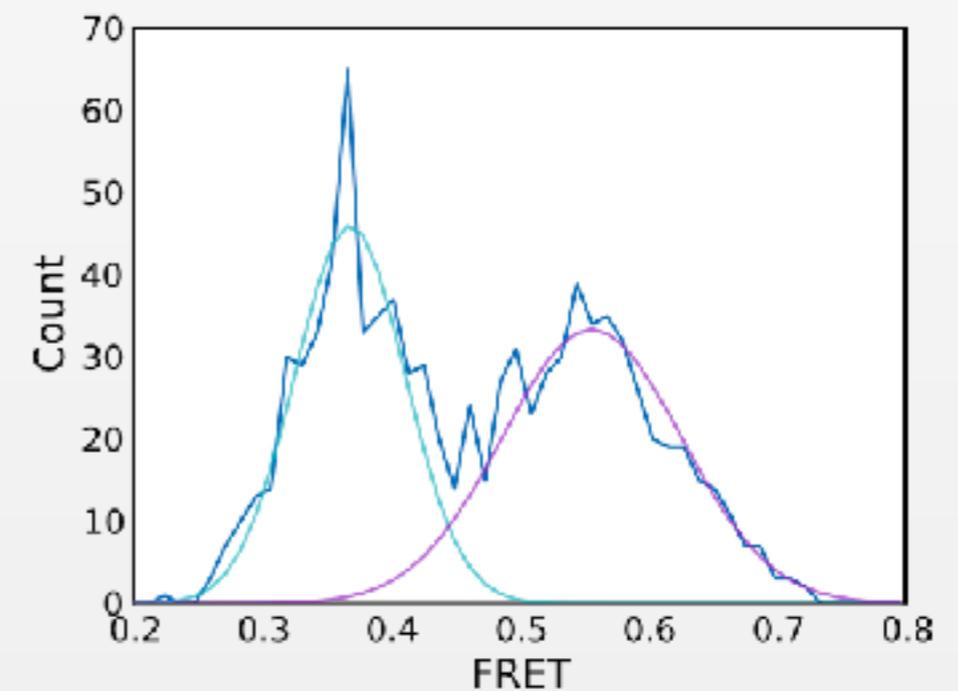
## Histogram



## Posterior on states

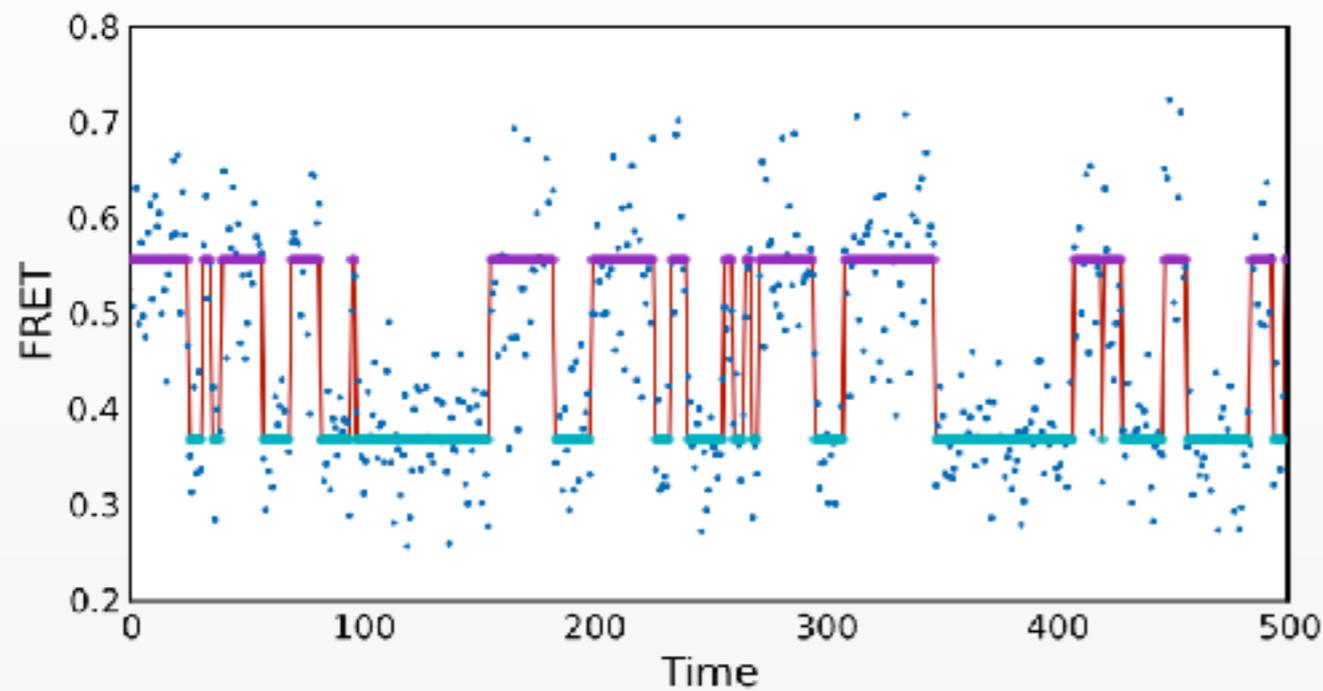


## Mixture

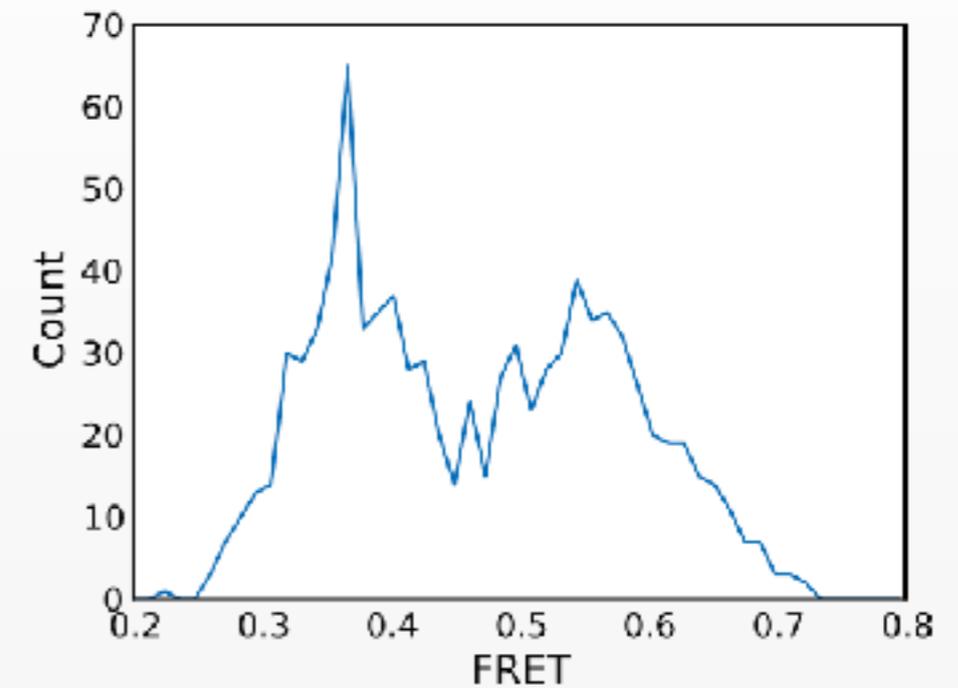


# Can we use a Gaussian Mixture Model?

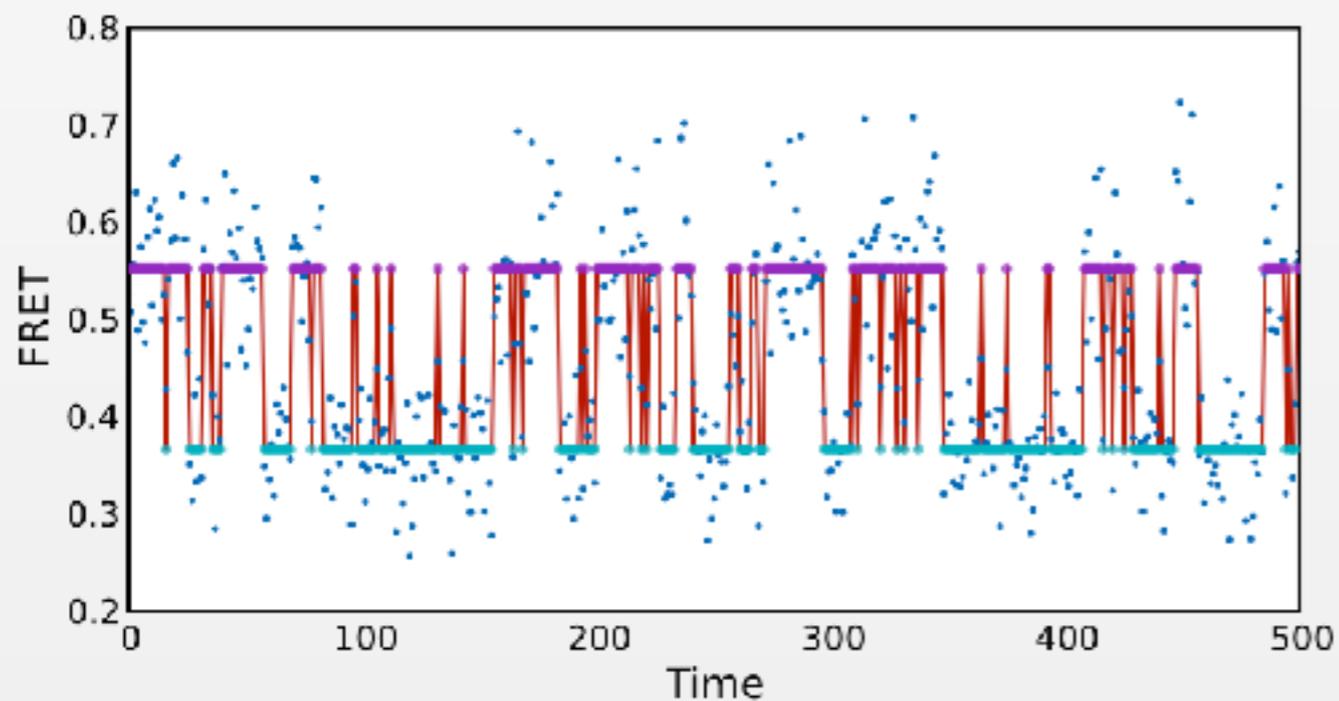
## Time Series



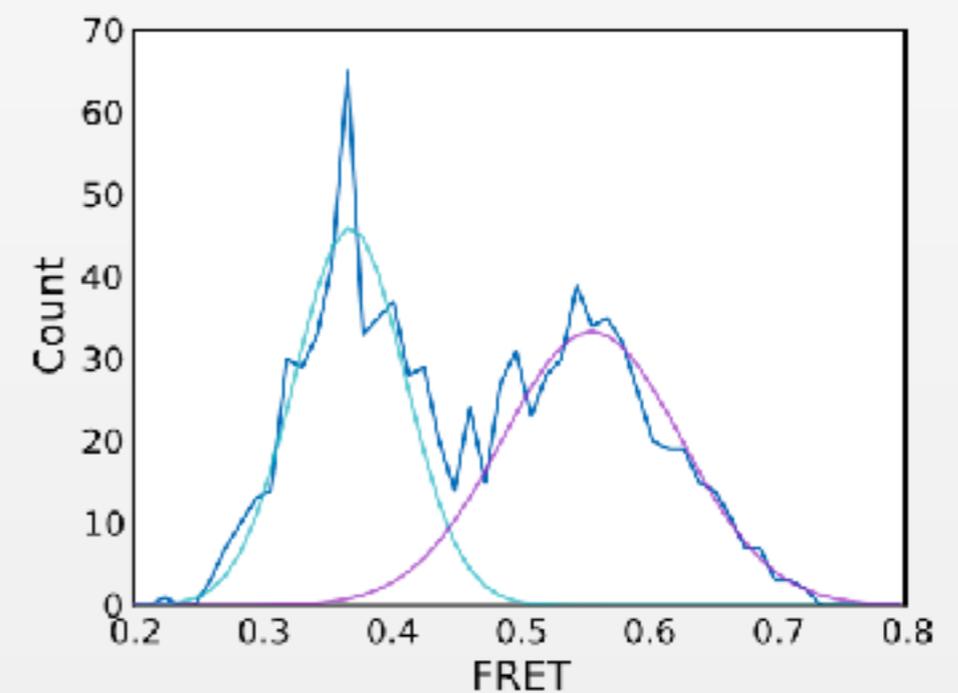
## Histogram



## Posterior on states

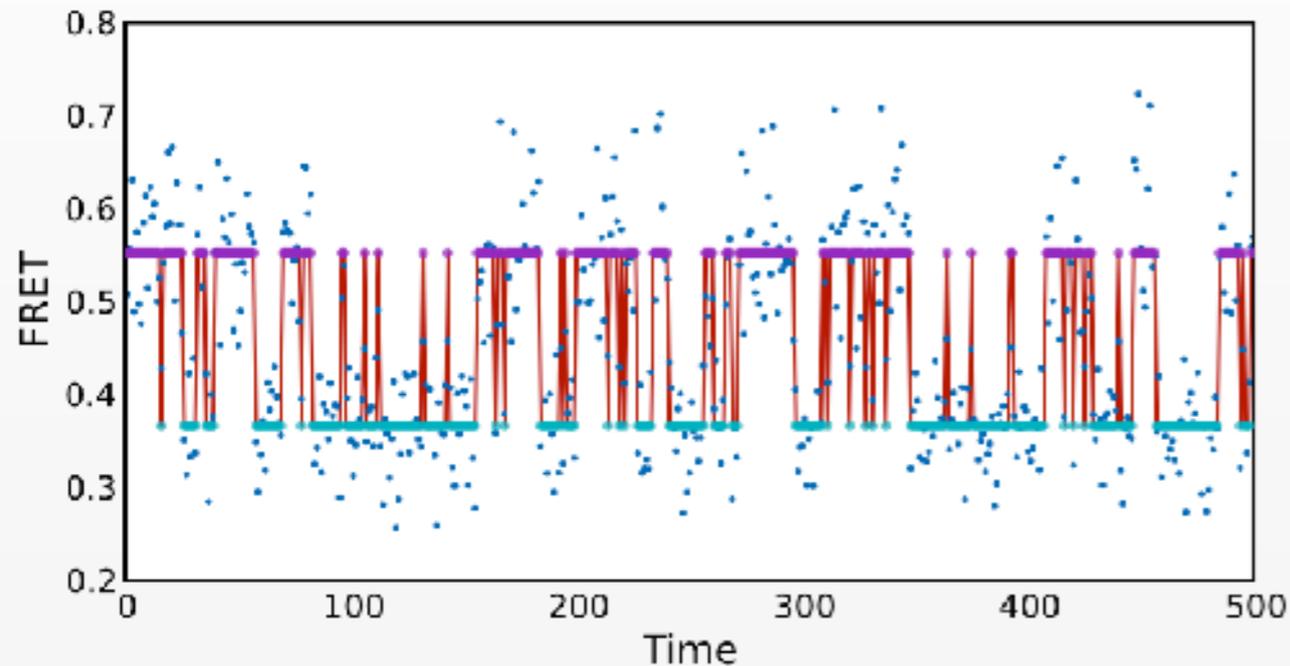


## Mixture

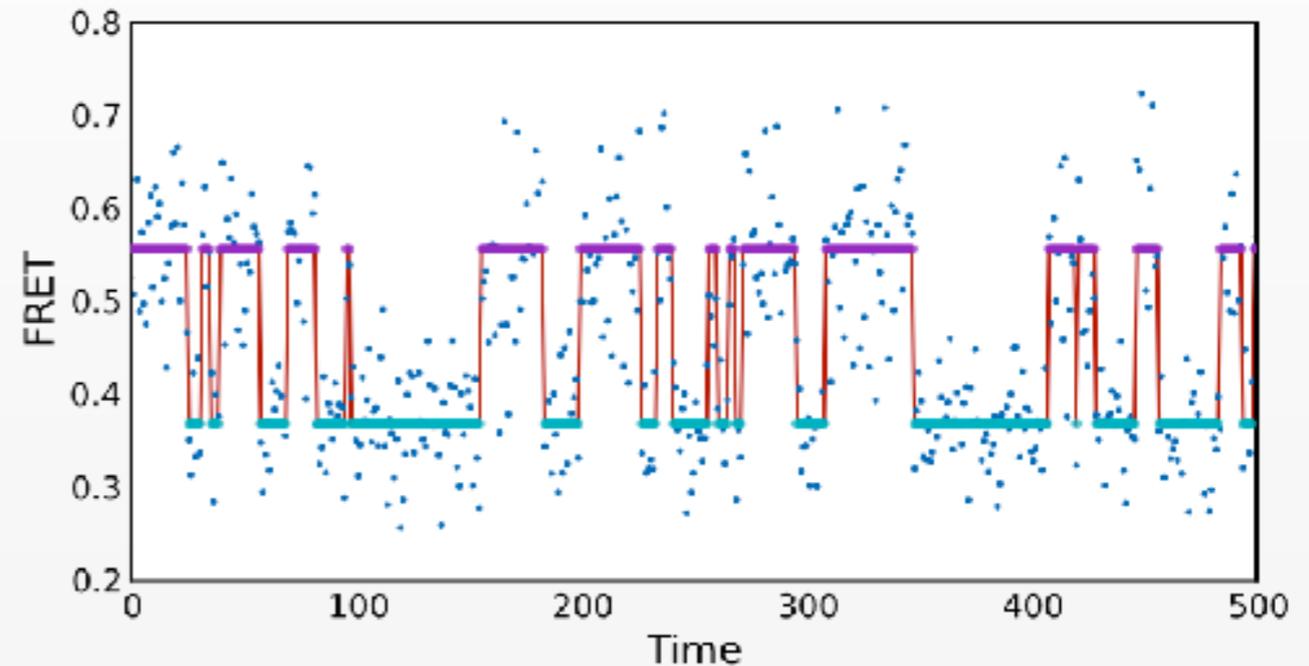


# Hidden Markov Models

Estimate from GMM

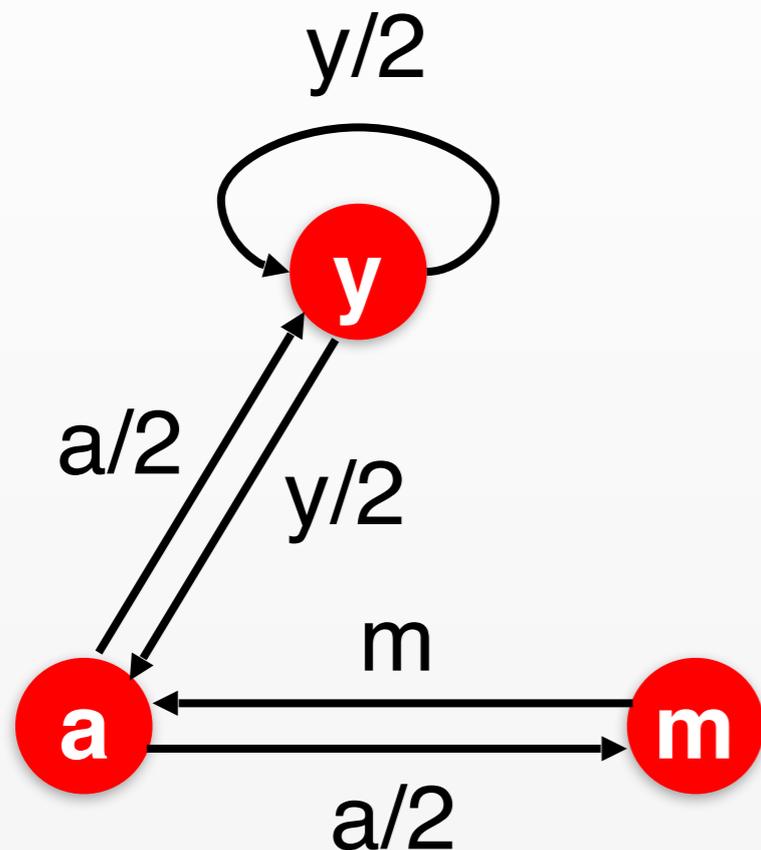


Estimate from HMM



- Idea: Mixture model + Markov chain for states
- Can model correlation between subsequent states (more likely to be in same state than different state)

# Reminder: Random Surfers in PageRank



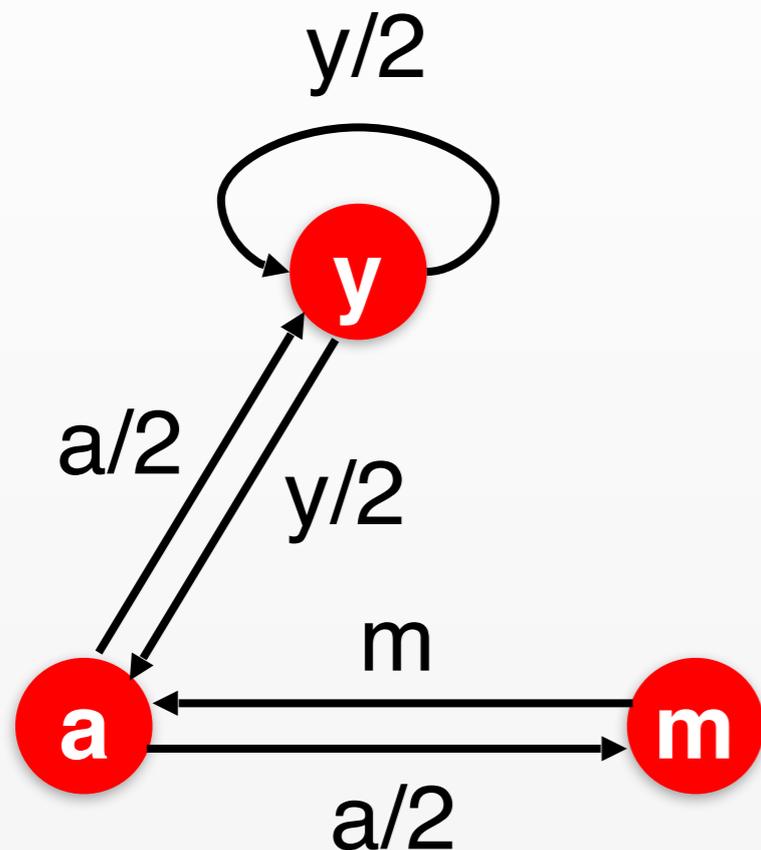
$$\mathbf{p}^t = M\mathbf{p}^{t-1} = M^t\mathbf{p}^0$$

$$\mathbf{p}^0 = \begin{bmatrix} 1/3 \\ 1/3 \\ 1/3 \end{bmatrix} \quad M = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} & 0 \\ \frac{1}{2} & 0 & 1 \\ 0 & \frac{1}{2} & 0 \end{bmatrix}$$

*Model for random Surfer:*

- At time  $t = 0$  pick a page at random
- At each subsequent time  $t$  follow an outgoing link at random

# Reminder: Random Surfers in PageRank



$$\mathbf{p}^t = M\mathbf{p}^{t-1} = M^t\mathbf{p}^0$$

$$\mathbf{p}^0 = \begin{bmatrix} 1/3 \\ 1/3 \\ 1/3 \end{bmatrix} \quad M = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} & 0 \\ \frac{1}{2} & 0 & 1 \\ 0 & \frac{1}{2} & 0 \end{bmatrix}$$

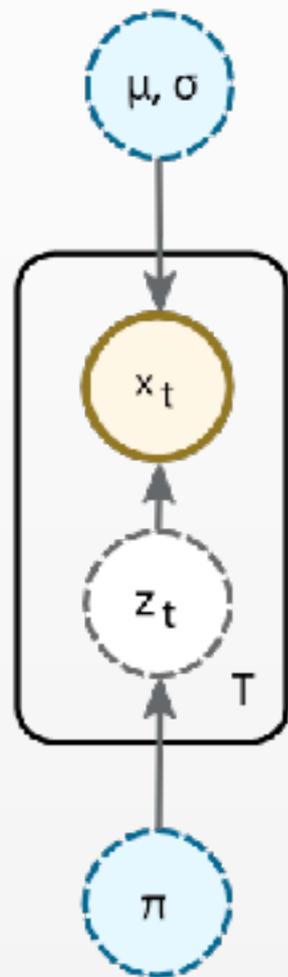
$$p(z_0 = i) = 1/N$$

$$p(z_t = i | z_{t-1} = j) = M_{ij}$$

$$\begin{aligned} p(z_t = i) &= \sum_j p(z_t = i, z_{t-1} = j) \\ &= \sum_j M_{ij} p(z_{t-1} = j) \end{aligned}$$

# Hidden Markov Models

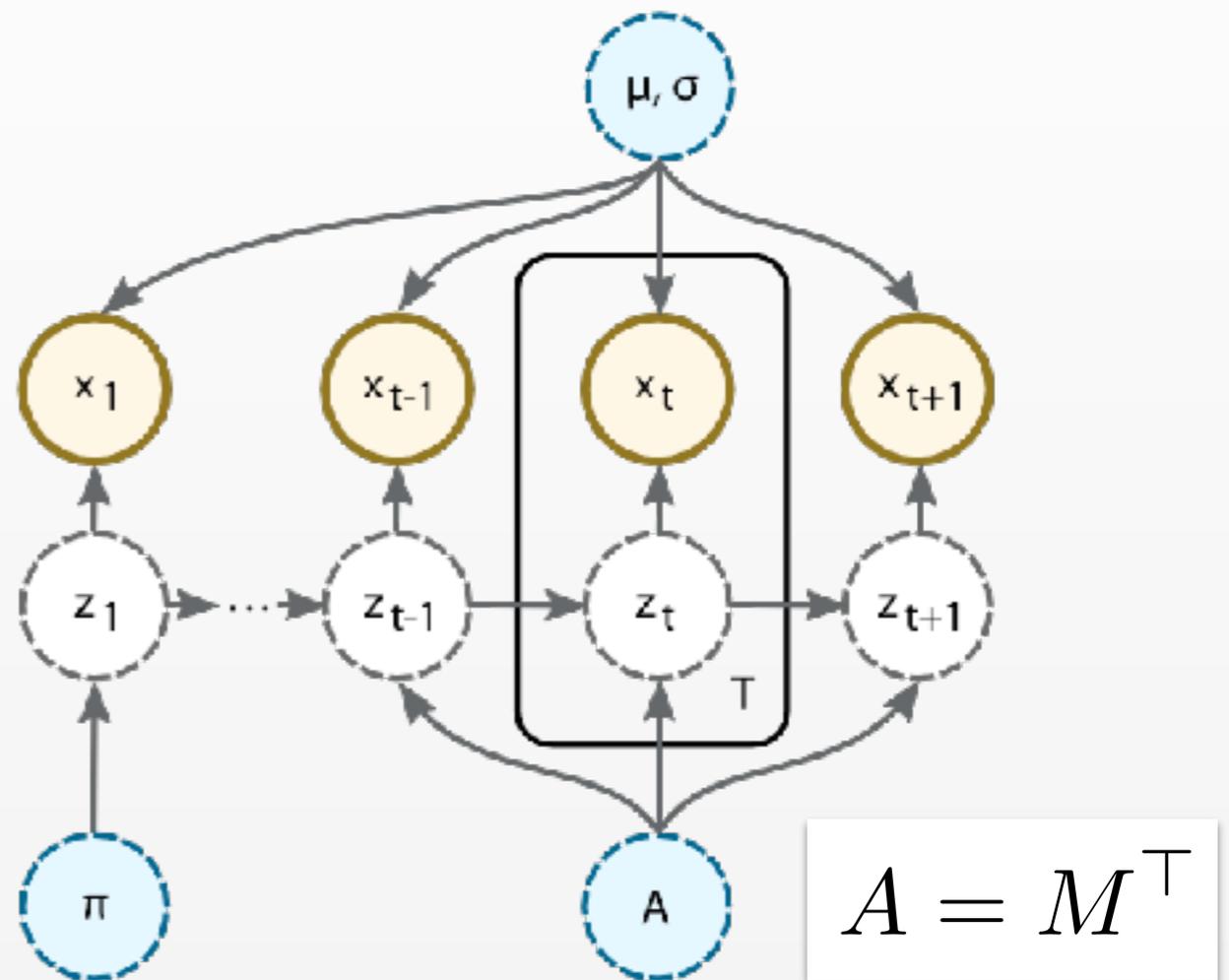
Gaussian Mixture



$$z_n \sim \text{Discrete}(\boldsymbol{\pi})$$

$$x_n | z_n = k \sim \text{Normal}(\mu_k, \sigma_k)$$

Gaussian HMM

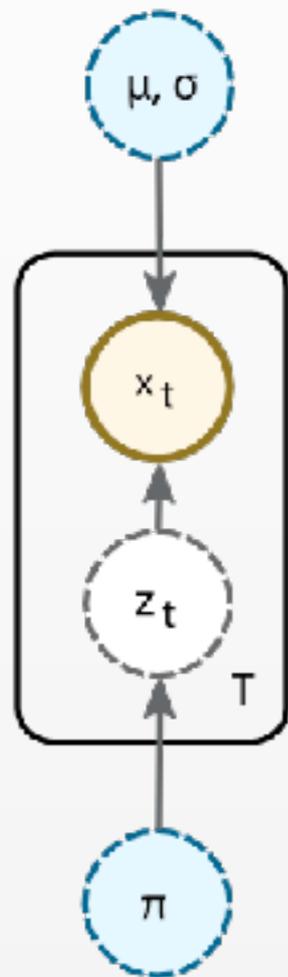


$$z_1 \sim \text{Discrete}(\boldsymbol{\pi})$$

$$z_{t+1} | z_t = k \sim \text{Discrete}(A_k)$$

$$x_t | z_t = k \sim \text{Normal}(\mu_k, \sigma_k)$$

# Review: Gaussian Mixtures



$$z_n \sim \text{Discrete}(\boldsymbol{\pi})$$

$$x_n | z_n = k \sim \text{Normal}(\mu_k, \sigma_k)$$

## *Expectation Maximization*

1. Update cluster probabilities

$$\begin{aligned} \gamma_{tk}^i &= p(z_t = k | x_t, \boldsymbol{\theta}^{i-1}) \\ &= \frac{p(x_t, z_t = k | \boldsymbol{\theta}^{i-1})}{\sum_l p(x_t, z_t = l | \boldsymbol{\theta}^{i-1})} \end{aligned}$$

2. Update parameters

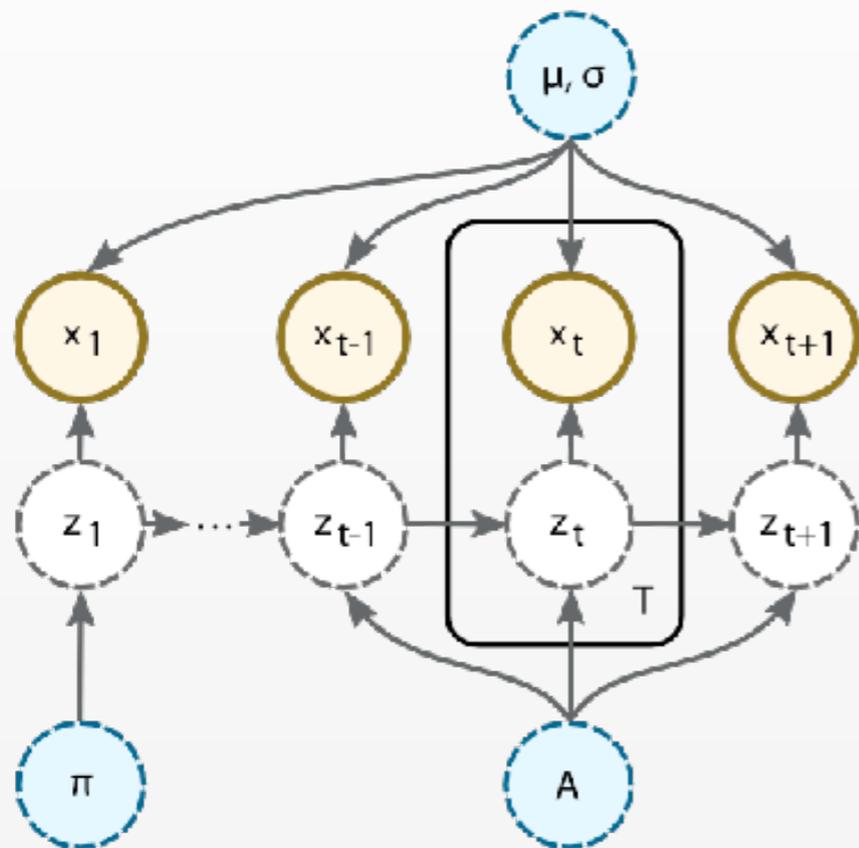
$$\mu_k^i = \frac{1}{N_k^i} \sum_{t=1}^T \gamma_{tk}^i x_t$$

$$\sigma_k^i = \left( \frac{1}{N_k^i} \sum_{t=1}^T \gamma_{tk}^i (x_t^i - \mu_k^i)^2 \right)^{1/2}$$

$$\pi_k^i = N_k^i / N \quad N_k^i = \sum_{t=1}^T \gamma_{tk}^i$$

# Forward-backward Algorithm

## *Expectation step for HMM*



$$z_1 \sim \text{Discrete}(\pi)$$

$$z_{t+1} | z_t = k \sim \text{Discrete}(A_k)$$

$$x_t | z_t = k \sim \text{Normal}(\mu_k, \sigma_k)$$

$$\gamma_{t,k} = p(z_t = k | x_{1:T}, \theta)$$

$$= \frac{p(x_{1:t}, z_t) p(x_{t+1:T} | z_t)}{p(x_{1:T})}$$

$$\propto \alpha_{t,k} \beta_{t,k}$$

$$\alpha_{t,l} := p(x_{1:t}, z_t)$$

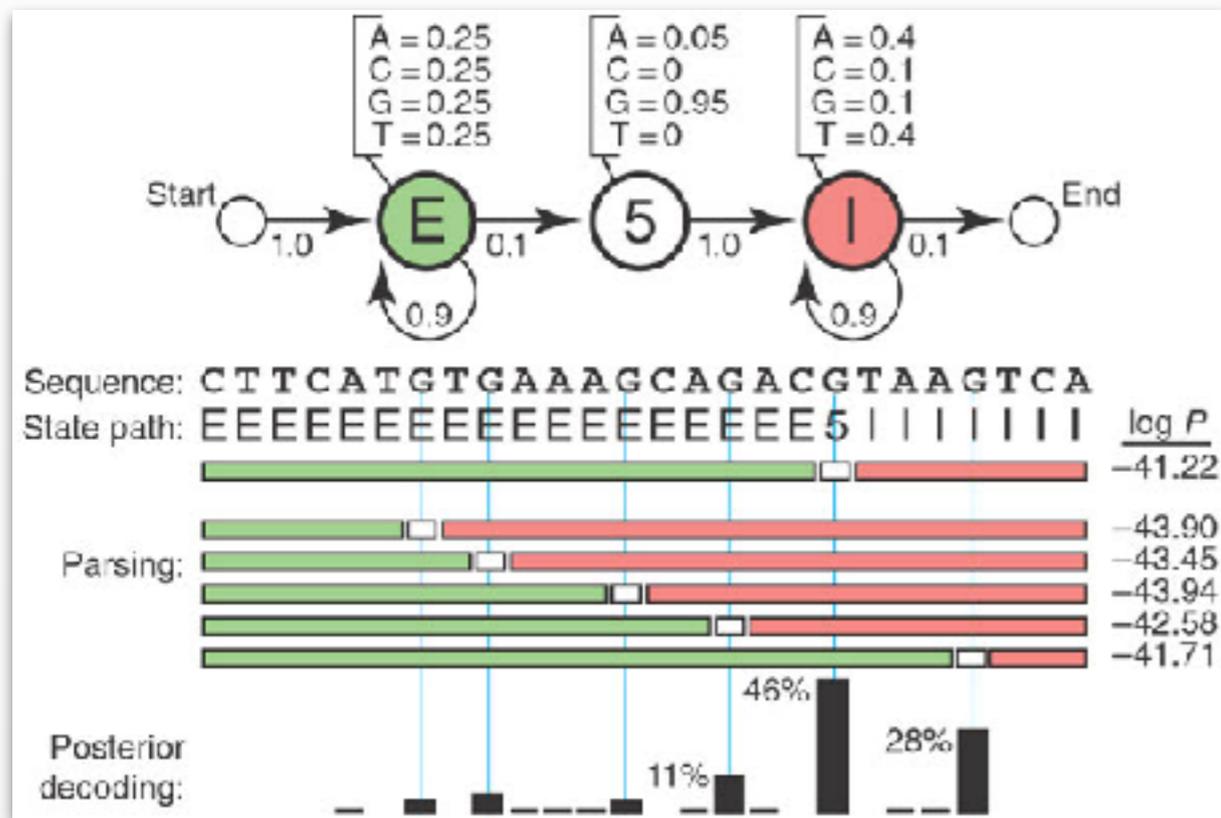
$$= \sum_k p(x_t | \mu_l, \sigma_l) A_{kl} \alpha_{t-1,k}$$

$$\beta_{t,k} := p(x_{t+1:T} | z_t)$$

$$= \sum_l \beta_{t+1,l} p(x_{t+1} | \mu_l, \sigma_l) A_{kl}$$

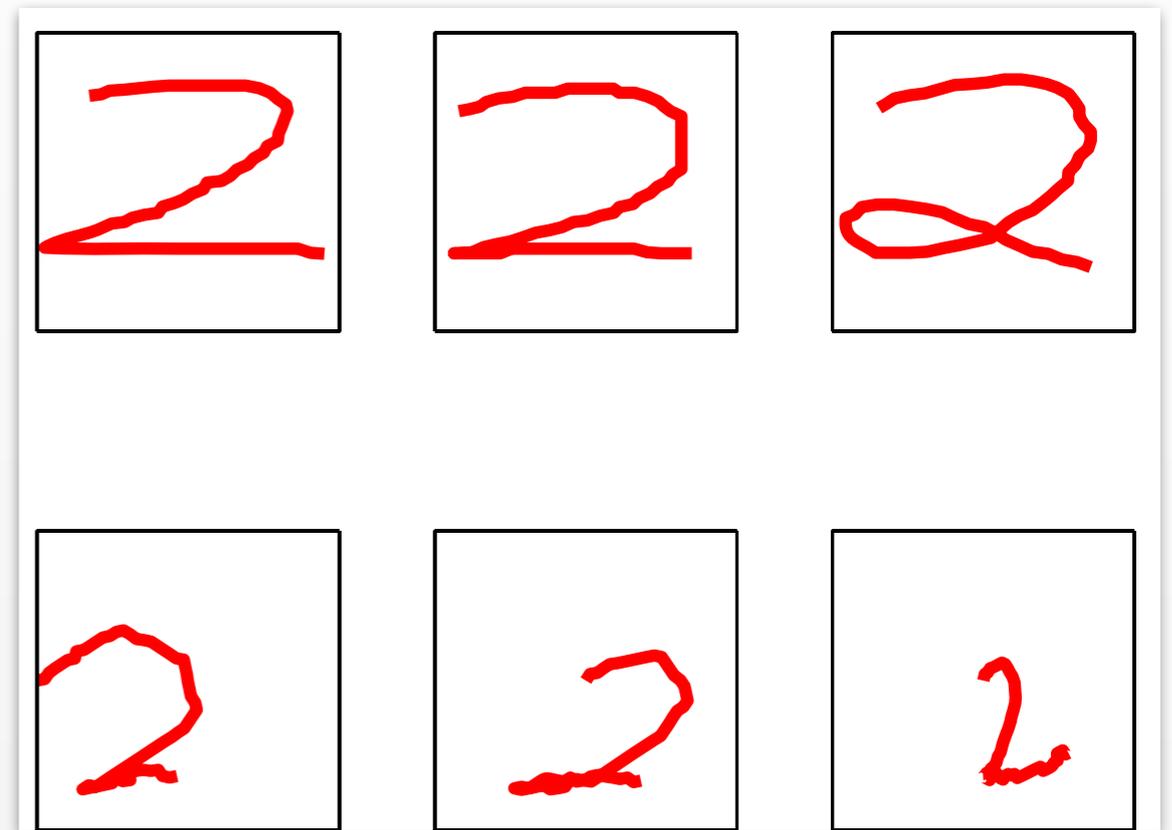
# Other Examples for HMMs

## RNA splicing



- State 1: Exon (relevant)
- State 2: Splice site
- State 3: Intron (ignored)

## Handwritten Digits



- State 1: Sweeping arc
- State 2: Horizontal line